

Model Synchronization in a Joint-Cognitive Paradigm

Mathsig Presentation

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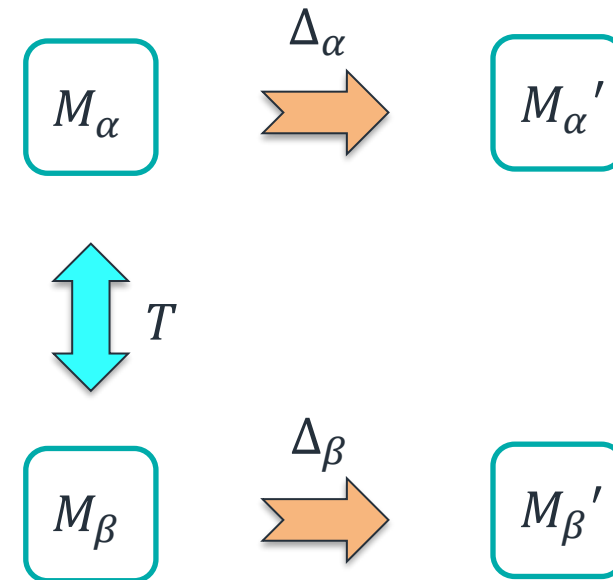
Context & Motivation

- Some challenges observed in practicing MBSE methodologies
 - How to maintain consistency between models?
 - How can we establish traceability without messing up the model complexity?
 - How do we handle change impacts in models?
- Our solution: **Model Synchronisation** with Structure Preserving Transformations [1]

What is Model Synchronisation?

- Two **consistent** models, M_α and M_β
- A change made to a M_α , denoted as Δ_α
- Synchronisation means [2]

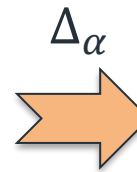
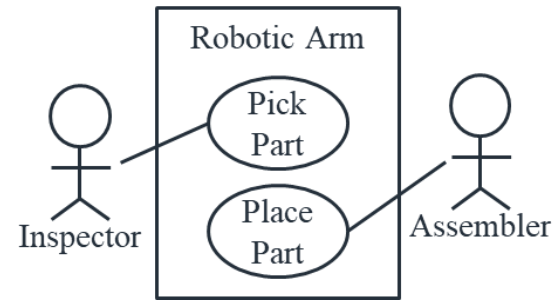
a change Δ_β is mandatory to M_β in order to maintain the consistency between M_α' and M_β'
- Issues with manual synchronisation: labour intensive, error-prone, lacking generality & repeatability
- Proposal: Semi-automated, model transformations, T , following a **joint cognitive** approach



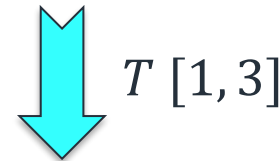
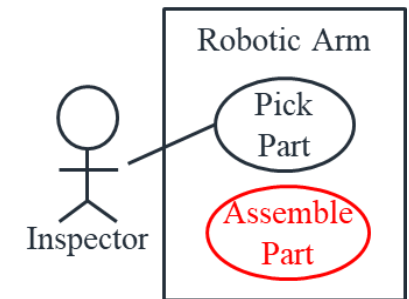
Robotic Arm Example

- Scenario:
 - Inspector checks the part, if OK
 - Robotic Arm then **picks** the part and **places** it on Assembler's workbench
 - Assembler finally assembles the part
- Change to functionality:
 - From Pick & Place, to Pick & Assemble
- Benefit:
 - Higher efficiency with reduced safety risks

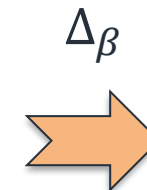
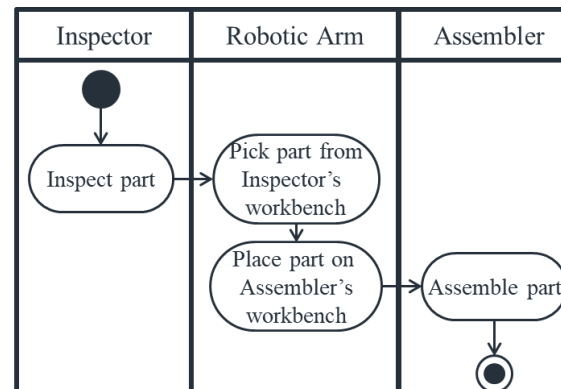
M_α : Use Cases



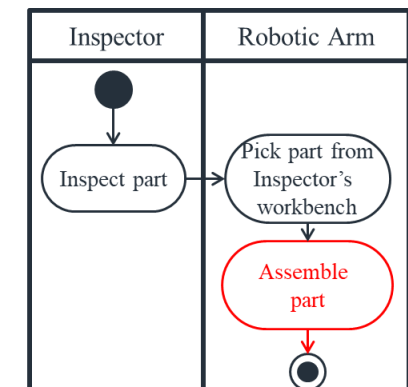
M_α' : Revised Use Cases



M_β : Activities

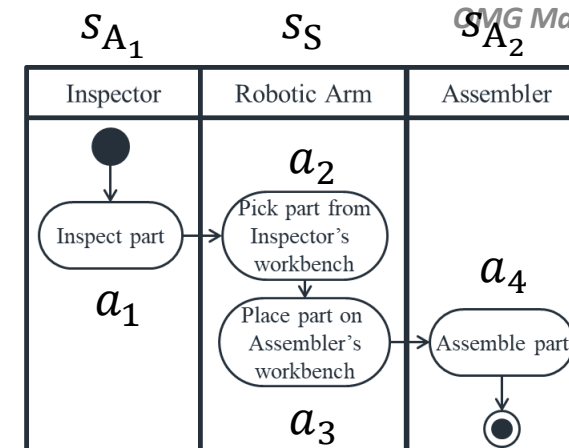


M_β' : Revised Activities

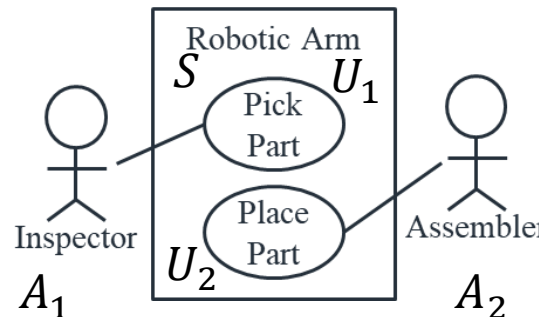


Matrix Representation

- Row/Column Headers: **model elements**
- Matrix element: **dependencies**
- $W_{i,j}$: **in-model dependencies**,
e.g., A_1 is associated with U_1
- $Q_{i,j}$: **cross-model dependencies**
e.g., A_1 is concordant with S_{A_1}
e.g., U_1 is decomposed into a_2



							s_S
							s_{A_1}
							s_{A_2}
							a_1
	$W_{a_1, s_{A_1}}$			W_{a_1, a_2}			a_2
W_{a_2, s_S}					W_{a_2, a_3}		a_3
W_{a_3, s_S}						W_{a_3, a_4}	a_4
		$W_{a_4, s_{A_2}}$					



	S	A_1	A_2	U_1	U_2
				W_{A_1, U_1}	
					W_{A_2, U_2}
$W_{U_1, S}$					
$W_{U_2, S}$					

	s_S	s_{A_1}	s_{A_2}	a_1	a_2	a_3	a_4
S	Q_{S, s_S}						
A_1		$Q_{A_1, s_{A_1}}$		Q_{A_1, a_1}			
A_2			$Q_{A_2, s_{A_2}}$				Q_{A_2, a_4}
U_1					Q_{U_1, a_2}		
U_2						Q_{U_2, a_3}	

Summary

- Users can follow any MBSE methodology to develop initially **consistent** diagrams/models
- The tool should **maintain the consistency** in the absence of explicitly modelled cross-model dependencies.
- This is achieved through **model synchronisation** enabled by **model transformation**
- A joint-cognitive approach. For example: the tool analyses elements being affected by a change while user decides how to make consistent changes to the affected elements.
- MapleMBSE – clearly has the capability for capturing in-model dependencies, but what about cross-model dependencies?

References

- [1] Ji, S., Wilkinson, M., & Dickerson, C. E. (2022). Structure Preserving Transformations for Practical Model-based Systems Engineering. To appear in *8th IEEE International Symposium on Systems Engineering, ISSE2022*, *arXiv preprint* <https://arxiv.org/abs/2209.07935>
- [2] Hettel, T., Lawley, M., & Raymond, K. (2008, July). Model synchronisation: Definitions for round-trip engineering. In *International Conference on Theory and Practice of Model Transformations* (pp. 31-45). Springer, Berlin, Heidelberg.
- [3] Dickerson, C. E., & Ji, S. (2021). *Essential Architecture and Principles of Systems Engineering*. CRC Press.